# Stationary Rational Bubbles in Non-Linear Business Cycle Models

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Main result: non-linear DSGE models have more stationary equilibria than you think!

This paper shows: <u>standard NON-LINEAR</u> <u>DSGE models have MULTIPLE stationary</u> <u>equilibria, even when the linearized versions</u> of these models have unique solution

⇒ In <u>non-linear</u> model: stationary fluctuations WITHOUT shocks to TFP, preferences, policy

⇒ Blanchard & Kahn (1980): conditions for existence of unique stable solution of linear(ized) models are IRRELEVANT for nonlinear models

# ⇒ Sunspot equilibria in non-linear models studied here look like 'BUBBLES':

- economy may temporarily diverge from steady state;
- with exogenous probability economy later reverts to steady state

# **BOOM-BUST CYCLE:**

- consistent with rational expectations
- 'rational bubbles' are stationary

Similarities and important differences with rational bubbles in linear models (Blanchard, 1979)

 Like Blanchard (1979) I focus on <u>models</u> whose linearized versions have unique nonexplosive equilibrium

• Key difference: bubbles in <u>non-linear</u> models are <u>STATIONARY</u>

Blanchard bubbles (linear models):
 *expected* trajectories <u>explode</u> to ± ∞

Consider non-linear model with just 1 nonpredetermined variable (no exogenous driver)  $E_t G(Y_{t+1}, Y_t) = 0$ 

Linearization (around steady state):  $E_t y_{t+1} = \lambda \cdot y_t$ ,  $y_t \equiv Y_t - Y^{SS}$ 

Linearized model has unique non-explosive solution iff  $|\lambda| > 1$ . Unique solution is:  $y_t = 0$  (Blanchard & Kahn (1980), Prop. 1)

 $E_t y_{t+1} = \lambda \cdot y_t$ ,  $\lambda > 1$ ;  $y_t$ : scalar jump variable Unique stable solution:  $y_t = 0$ 

# Blanchard (1979)

Bubble:  $y_{t+1} = (\lambda/(1-\pi)) \cdot y_t$  with probability  $1 - \pi$   $y_{t+1} = 0$  with probability  $\pi$   $\lim_{s \to \infty} E_t y_{t+s} = \pm \infty$  if  $y_t \neq 0$ **expected path of bubble diverges to \pm \infty** 

# Expected path of bubbles in <u>non-linear</u> DSGE described here do NOT diverge to ±∞

• Explosive (expected) trajectories are problematic:

accuracy of linear model approximations breaks down far from point of approximation; non-negativity & technological feasibility constraints may be violated

Example: with decreasing returns to capital, explosive trajectory of capital & output is INFEASIBLE

⇒ LINEAR APPROXIMATION UNSUITABLE FOR ANALYZING RATIONAL BUBBLES  By contrast: <u>non-linear</u> analysis here takes non-negativity constraints, decreasing returns & risk aversion into account

 Decreasing returns & risk aversion generate stabilizing forces that prevent explosive trajectories

 Stationary rational bubbles in <u>non-linear</u> models are generally <u>one-sided</u> (capital over-accumulation, but no underaccumulation)
 [By contrast: Blanchard bubbles in linear models can be positive or negative]  Rational bubbles in <u>non-linear</u> model can induce fluctuations that are <u>close to</u> <u>deterministic steady state most of the time</u>

⇒ unconditional mean of endogenous variables close to deterministic steady state

 Non-linear DSGE models driven just by stationary bubbles can generate <u>persistent</u> <u>fluctuations of real activity</u> & <u>capture key</u> <u>business cycle stylized facts</u>

# Note: Can construct DSGE models whose linearized versions have stable sunspots:

$$\begin{split} E_{t}y_{t+1} = \lambda \cdot y_{t} & \text{need } |\lambda| \leq 1. \Rightarrow y_{t+1} = \lambda \cdot y_{t} + \varepsilon_{t+1} \text{ is stationary} \\ \text{solution for } \underline{\text{any}} \{\varepsilon_{t+1}\} \text{ with } E_{t}\varepsilon_{t+1} = 0 \end{split}$$

Needed ingredients:

- Increasing returns, externalities (e.g., Schmitt-Grohé (1997), Benhabib and Farmer (1999))
- Financial frictions (e.g., Martin and Ventura (2018))
- Overlapping generations (e.g., Woodford (1986), Galí (2018))

Specific assumptions & calibrations that deliver  $|\lambda| < 1$  can be debatable & fragile (e.g. in standard OLG model: need r≤g) By contrast, paper here argues that very standard DSGE models with  $|\lambda| > 1$  can deliver stationary sunspot equilibria, if non-linearities are considered.

# **Related contributions**

 Bacchetta, van Wincoop & Tille "Selffulfilling Risk Panics" (AER 2012): stylized asset pricing model whose linearized version has unique solution, but non-linear model has multiple equilibria iff sunspot shocks are HETEROSKEDASTIC. My paper highlights importance of heteroskedasticity for bubbles in non-linear **DSGE** business cycle model.

 Holden (2016ab) shows that multiple equilibria emerge when occasionally binding constraints (e.g. ZLB) are integrated into otherwise standard linear model.

By contrast: my analysis considers FULLY <u>non-linear</u> models.

**All model equations are non-linear** 

All relevant non-negativity constraints are imposed.

 Model solutions here are globally accurate.
 Multiple equilibria here have "bubbly" dynamics (different from Holden, 2016ab)

# **Basic intuition I:**

Consider non-linear model with just 1 nonpredetermined variable (no exogenous driver)  $E_t G(Y_{t+1}, Y_t) = 0$ 

Linearization (around steady state):  $E_t y_{t+1} = \lambda \cdot y_t$ ,  $y_t \equiv Y_t - Y^{SS}$ 

Linearized model has unique non-explosive solution iff  $|\lambda| > 1$ . Unique solution is:  $y_t = 0$  (Blanchard & Kahn (1980), Prop. 1)

# • RESULT

Even when  $|\lambda| > 1$ , the **non-linear** model can have stationary sunspot equilibrium

# • IDEA

$$\begin{split} &E_t G(Y_{t+1},Y_t) = 0 \iff G(Y_{t+1},Y_t) = \mathcal{E}_{t+1} \quad \text{with} \ E_t \mathcal{E}_{t+1} = 0 \\ &\Rightarrow Y_{t+1} = \Lambda(Y_t,\mathcal{E}_{t+1}) \quad \mathcal{E}_{t+1} \colon \text{``sunspot shock''} \\ &\text{Even if } |\Lambda_Y| > 1, \text{ there may exist process } \{\mathcal{E}_{t+1}\} \\ &\text{with} \ E_t \mathcal{E}_{t+1} = 0 \text{ such that } \{Y_{t+1}\} \text{ is stationary.} \end{split}$$

Note: when white noise  $\{\varepsilon_{t+1}\}$  is fed into  $Y_{t+1} = \Lambda(Y_t, \varepsilon_{t+1})$ , then  $\{Y_{t+1}\}$  diverges if  $|\Lambda_Y| > 1$ .

Key requirements for stationary solution: •  $Y_{t+1} = \Lambda(Y_t, \varepsilon_{t+1})$  has to be NON-LINEAR in  $\varepsilon_{t+1}$ • Distribution of  $\mathcal{E}_{t+1}$  has to depend on  $Y_t$  $Y_{t+1} \cong \Lambda(Y_t, 0) + \Lambda_{\varepsilon}(Y_t, 0) \cdot \mathcal{E}_{t+1} + \frac{1}{2} \Lambda_{\varepsilon \varepsilon}(Y_t, 0) \cdot (\mathcal{E}_{t+1})^2$  $E_{t}Y_{t+1} \cong \Lambda(Y_{t}, 0) + \frac{1}{2}\Lambda_{\varepsilon\varepsilon}(Y_{t}, 0) \cdot E_{t}(\varepsilon_{t+1})^{2}$ Let  $E_t(\varepsilon_{t+1})^2 = f(Y_t) \ge 0$ . If  $\Lambda_{\varepsilon}(Y_t, 0) \ne 0$  then can set  $E_t(\mathcal{E}_{t+1})^2 = f(Y_t)$  such that  $|dE_tY_{t+1}/dY_t| < 1$ : **"MEAN REVERSION"** 

Example:  $\Lambda_Y(Y_t, 0) > 1$ ,  $\Lambda_{\varepsilon\varepsilon}(Y_t, 0) < 0$ . Then need  $f'(Y_t) > 0$  for mean reversion:  $E_t(\varepsilon_{t+1})^2$  must be increasing in  $Y_t$ .

**Basic intuition II: RBC model**  $C_t + K_{t+1} = Y_t; \quad Y_t = F(K_t), \quad F' > 0, \quad F'' < 0$  $\beta\{[E_{t}u'(C_{t+1})]/u'(C_{t})\}\cdot F'(K_{t+1})=1; \text{ assume } u'''>0 (CRRA)$ Sunspot: assume  $K_{t+1} \uparrow \Rightarrow C_t \downarrow u'(C_t) \uparrow, F'(K_{t+1}) \downarrow$ Euler eqn requires:  $E_t u'(C_{t+1}) = E_t u'(F(K_{t+1}) - K_{t+2})$ • In <u>deterministic</u> economy: need  $C_{t+1} \checkmark \& K_{t+2}$ ,  $\uparrow$  $K_{t+2}$  has to rise <u>more</u> than  $K_{t+1} ! \Rightarrow K diverges$ • With stochastic sunspot:  $K_{t+2}$  random.  $u'(C_{t+1})$  is convex in  $K_{t+2} \Rightarrow \text{ if } Var_t(K_{t+2})$  rises,  $E_t u'(C_{t+1}) \uparrow \Rightarrow E_t K_{t+2}$  can rise less than  $K_{t+1}$ !  $\Rightarrow$  possibility of mean reversion

TRANSVERSALITY CONDITION (TVC) Standard DSGE usually assume an infinitely-lived representative agent. Optimality conditions include transversality condition:

$$\lim_{\tau \to \infty} \beta^{\tau} E_t u'(C_{t+\tau}) K_{t+\tau+1} > 0$$

# TVC + Euler eqn. + static efficiency condit. $\Rightarrow$ unique equilibrium.

## When TVC does not hold: economy is "dynamically inefficient"

# **THIS PAPER DISREGARDS TVC**

Goal is to establish existence of stationary rational bubbles in <u>non-linear</u> DSGE models
Explosive bubbles in linear (Blanchard) too violate TVC

JUSTIFICATIONS OF MODELS WITHOUT TVC Assume that there is no TVC because agents are finitely lived (N periods) Novel result about OLG economy:

Assume: (I) Complete financial market that allows all generations alive at both dates *t* and *t*+1 (II) each generation receives wealth endowment such that consumption by newborns is time-invariant share of aggregate consumption. (Under log-utility: wealth endowment of newborns has to be timeinvariant share of total wealth)

#### THEN

an 'aggregate' Euler equation holds that is identical to the Euler equation of a representative infinitely lived household:

$$\beta E_t \{ u'(C_{t+1}) / u'(C_t) \} MPK_{t+1} = 1$$

BUT: there is no TVC in the OLG economy!

# OLG structure with efficient intergenerational risk sharing:

justification for macro models that lacks a TVC, but whose other equilibrium conditions are identical to those of standard business cycle models (that assume infinitely lived agents) Other justifications for disregarding TVC 1) Lansing (2010) disregards the TVC in a Lucasstyle asset pricing models with bubbles, arguing that "agents are forward-looking but not to the extreme degree implied by the transversality condition"

2) In richer models with heterogeneous agents and distortions: equilibrium is not solution of decision problem of representative agent.

Detection of TVC violations in stochastic economies: virtually impossible, even with very long simulation runs (billions of periods):

States with very low consumption might only occur with extremely small probabilities.

**Detailed Example I:** Long-Plosser RBC model with sunspots  $u(C) = \ln(C); C_t + K_{t+1} = Y_t; Y_t = F(K_t) \equiv (K_t)^{\alpha}, 0 < \alpha < 1$ Euler equation:  $\beta E_t \{ u'(C_{t+1})/u'(C_t) \} \cdot F'(K_{t+1}) = 1$  $\Rightarrow \beta E_{t} \{ C_{t} / C_{t+1} \} \cdot \alpha Y_{t+1} / K_{t+1} = 1$  $\Rightarrow \beta E_t \{ (Y_t - K_{t+1}) / (Y_{t+1} - K_{t+2}) \} \cdot \alpha Y_{t+1} / K_{t+1} = 1$  $\Rightarrow \alpha \beta \cdot E_{t} \{ (1 - K_{t+1}/Y_{t}) / (1 - K_{t+2}/Y_{t+1}) \} \cdot Y_{t}/K_{t+1} = 1$ 

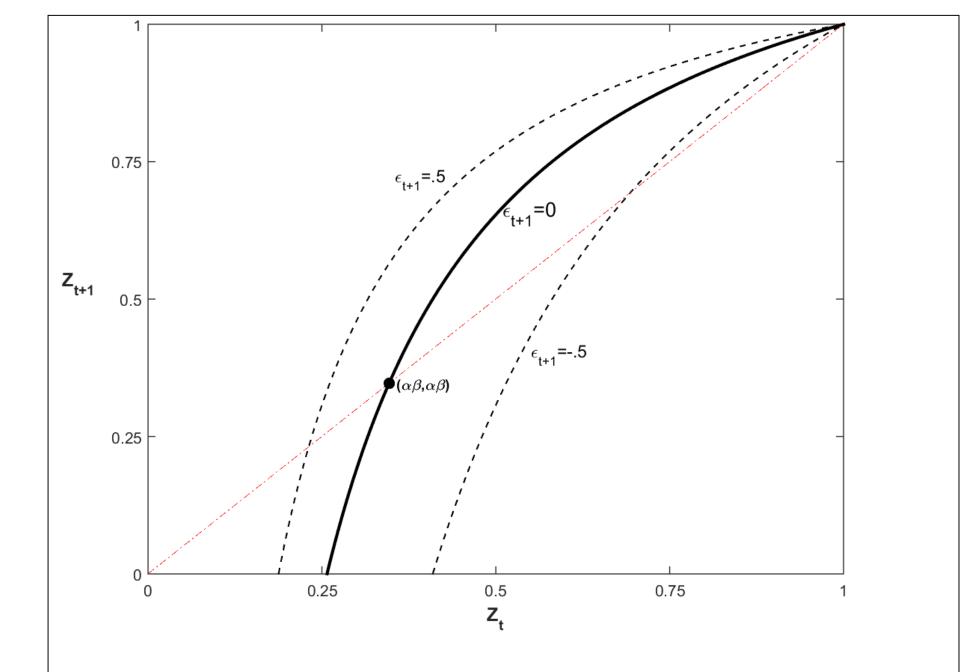
 $\Rightarrow \alpha\beta \cdot E_t \{ (1-Z_t)/(1-Z_{t+1}) \}/Z_t = 1, \\ Z_t \equiv K_{t+1}/Y_t : \text{ investment/output ratio} \\ \text{Textbook solution: } Z_t = \alpha\beta$ 

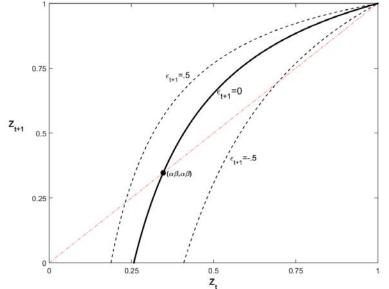
 $\begin{aligned} \alpha\beta \cdot E_t \{ (1-Z_t)/(1-Z_{t+1}) \}/Z_t &= 1 \\ \text{Linearization around } Z = \alpha\beta \\ E_t z_{t+1} &= \lambda \cdot z_t, \quad z_t \equiv Z_t - Z; \quad \lambda \equiv 1/(\alpha\beta) > 1. \\ \Rightarrow z_t &= 0 \text{ is } \underline{\text{unique non-explosive solution of } \\ \underline{\text{linearized model}}. \end{aligned}$ 

# But: <u>non-linear</u> model has other stationary solutions.

$$\alpha\beta \cdot \{(1-Z_t)/(1-Z_{t+1})\}/Z_t = 1 + \varepsilon_{t+1}, \quad E_t \varepsilon_{t+1} = 0$$
$$\Rightarrow Z_{t+1} = \Lambda(Z_t, \varepsilon_{t+1}) \equiv 1 - \alpha\beta(1/Z_t - 1)/(1 + \varepsilon_{t+1}).$$

 $Z_{t+1}$  increasing & strictly concave in  $\mathcal{E}_{t+1}$ 





 $Z_{t+1} = \Lambda(Z_t, \varepsilon_{t+1}) \equiv 1 - \alpha \beta(1/Z_t - 1)/(1 + \varepsilon_{t+1})$ 

• When  $Z_t < \alpha \beta$ , the model can hit zero-capital corner solution in later periods  $\Rightarrow$  restrict attention to solutions with  $Z_\tau \in [\alpha \beta, 1) \quad \forall \tau$ 

•Support of  $\varepsilon_{t+1}$  has to be bounded below:  $\varepsilon_{t+1} \ge -1 + [\alpha \beta / (1 - \alpha \beta)] \cdot [1/Z_t - 1]$  $\Rightarrow$  distribution of  $\varepsilon_{t+1}$  must depend on  $Z_t$  !

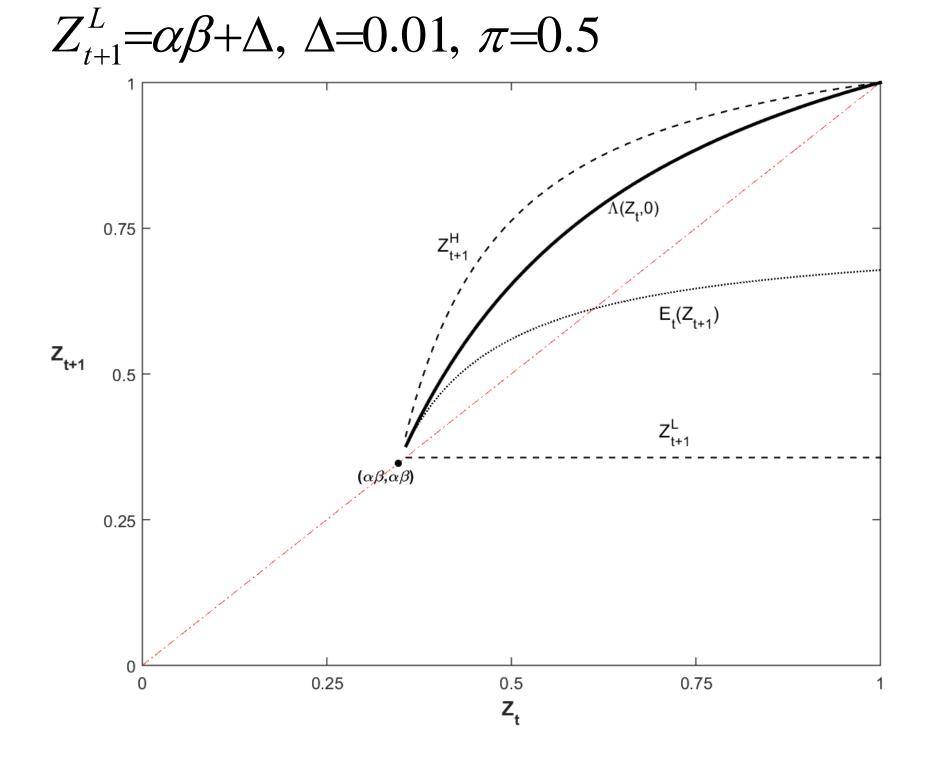
• Let  $\varepsilon_{t+1}$  only takes two values:  $-\overline{\varepsilon_t}$  and  $\overline{\varepsilon_t} \cdot \pi_t/(1-\pi_t)$  with probabilities  $\pi_t$  and  $1-\pi_t$ , respectively,  $\overline{\varepsilon_t} \in [0,1) \Longrightarrow Z_{t+1}$  takes two values:  $Z_{t+1}^L \equiv \Lambda(Z_t, -\overline{\varepsilon_t}) \& Z_{t+1}^H \equiv \Lambda(Z_t, \overline{\varepsilon_t}\pi_t/(1-\pi_t))$  with  $Z_{t+1}^L \leq Z_{t+1}^H \leq 1$ .

• Postulate  $Z_{t+1}^{L} = f(Z_t)$ , with  $\alpha \beta \leq f(Z_t) \leq \Lambda(Z_t, 0)$  for  $Z_t \in [\alpha \beta, 1)$ . Solve  $Z_{t+1}^{L} \equiv \Lambda(Z_t, -\overline{\varepsilon_t})$  for  $\overline{\varepsilon_t}$  & substitute into  $Z_{t+1}^{H} \equiv \Lambda(Z_t, \overline{\varepsilon_t} \pi_t/(1-\pi_t))$  Degrees of freedom in modeling sunspot:

- bust investment/GDP ratio,  $Z_{t+1}^L$
- conditional probability of bust,  $\pi_t$

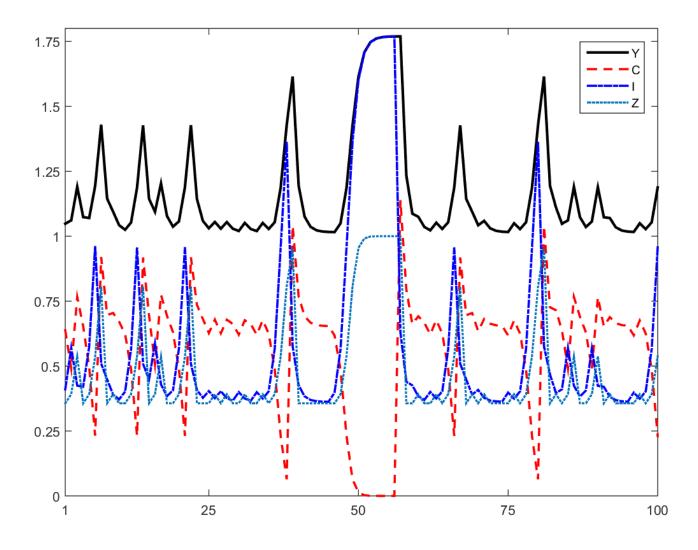
# **Specification I:** $Z_{t+1}^{L} = \alpha \beta + \Delta$ , $\Delta = 0.01$ , $\pi = 0.5$

(When  $\Delta=0$ , then  $Z=\alpha\beta=0.346$  is absorbing state; thus set  $\Delta>0$ )

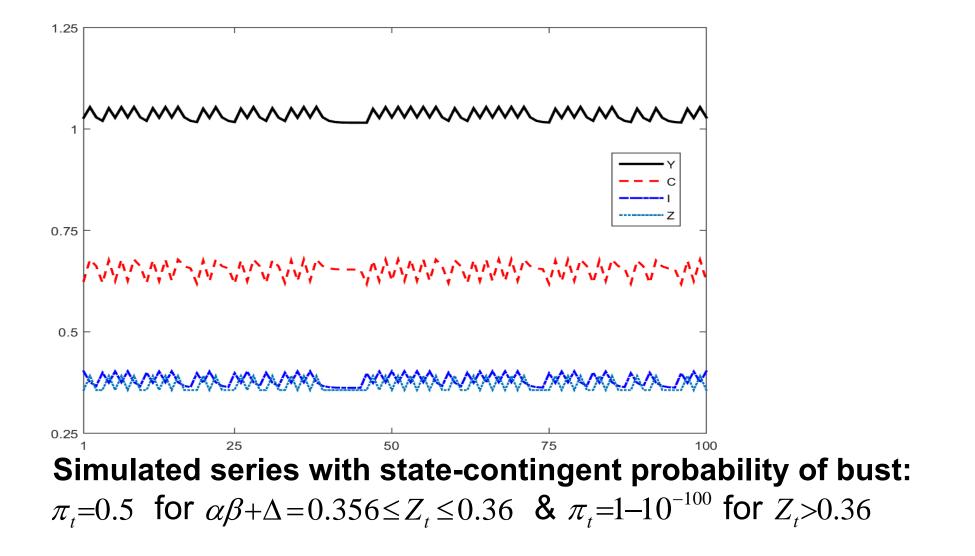


#### Simulated series with const. probability: $\pi$ =0.5

Simulated output (Y), consumption (C) and investment (I) normalized by steady state output



# Lower volatility if probability of investment bust rises once investment/output ration $Z_t$ crosses threshold.



	Stan	dard de	v. %	_Corr	<u>. with Y</u>		Autoco	orr.	Mea	n (% d	eviation	from
SS)												
	Y	С	Ι	С	Ι	Y	С	Ι	Y	С	Ι	Ζ
	(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)	(9)	(10)	(11)	(12)
(a) Specification	n I: $Z_t^{I}$	$L = \alpha \beta + \Delta$										
$\pi_t = 0.5$	11.72	100.19	33.48	-0.42	0.62	0.62	0.47	0.62	13.49	-7.62	53.31	31.15
$\pi_t \cong 1 \text{ for } z_t > 0.36$	1.33	3.51	3.82	0.77	-0.26	-0.26	-0.66	-0.26	3.27	-0.13	9.71	6.25
(b) US Data (fro	om Kir	ng and R	ebelo (19	99))								
	1.81	1.35	5.30	0.88	0.80	0.88	0.80	0.87				
Note: all busines	e etatie	tice nerts	in to HP_	filtered log	ned varial							

Table 1. Long-Plosser model with bubbles: predicted business cycle statistics

Note: all business statistics pertain to HP-filtered logged variables.

# Example II: RBC model with incomplete capital depreciation & endogenous labor

 $U(C_{t},L_{t})=\ln(C_{t})+\Psi\cdot\ln(1-L_{t}), \quad \Psi>0, \ L_{t}: \text{ hours worked}$  $C_{t}+K_{t+1}=Y_{t}+(1-\delta)K_{t}, \quad Y_{t}=\theta(K_{t})^{\alpha}(L_{t})^{1-\alpha}$ 

- FOCs:  $C_t \Psi/(1-L_t) = (1-\alpha)\theta(K_t)^{\alpha}(L_t)^{-\alpha}$  $E_t \beta\{C_t/C_{t+1}\}(\alpha\theta(K_{t+1})^{\alpha-1}(L_{t+1})^{1-\alpha}+1-\delta) = 1$
- Using static efficiency conditions can express C & L and functions of capital & TFP:

 $C_t = \gamma(K_{t+1}, K_t), L_t = \eta(K_{t+1}, K_t)$ 

Can writer Euler equation as:

 $E_{t}[\beta\{\gamma(K_{t+1},K_{t})/\gamma(K_{t+2},K_{t+1})\}(\alpha\theta(K_{t+1})^{\alpha-1}(\eta(K_{t+2},K_{t+1}))^{1-\alpha}+1-\delta)]=1$ 

Euler equation:  $E_t H(K_{t+2}, K_{t+1}, K_t) = 1$ 

No bubble solution (TVC): described by policy function  $K_{t+1} = \lambda(K_t)$ so that  $E_t H(\lambda(\lambda(K_t)), \lambda(K_t), K_t) = 1$  Consider <u>bubble equilibria</u> such that, for any *t*,  $K_{t+1}$  takes one of two values  $K_{t+1} \in \{K_{t+1}^L, K_{t+1}^H\}$ with exogenous probabilities  $\pi$  and  $1-\pi$ , where  $K_{t+1}^L = \lambda(K_t) e^{\Delta}$ ;

 $\Delta$ >0: small positive constant

'L' is 'bust' state, in which capital stock set at t reverts to value close to 'no-bubble' decision rule

Euler equation  $E_{t}H(K_{t+2}, K_{t+1}, K_{t}) = 1$ becomes:  $\pi H(\lambda(K_{t+1})e^{\Delta}, K_{t+1}, K_{t}) + (1-\pi) \cdot H(K_{t+2}^{H}, K_{t+1}, K_{t}) = 1$ 

### Economy evolves as follows:

At date t: random draw (with probab.  $\pi$ , 1- $\pi$ ) determines  $K_{t+1} \in \{K_{t+1}^L, K_{t+1}^H\}$  where  $K_{t+1}^L = \lambda(K_t)e^{\Delta}$ 

Euler equation between t and t+1 determines  $K_{t+2}^{H}$ :  $\pi H(\lambda(K_{t+1})e^{\Delta}, K_{t+1}, K_{t}) + (1-\pi) \cdot H(K_{t+2}^{H}, K_{t+1}, K_{t}) = 1$ 

Etc. in all subsequent periods.

See paper for: • Existence proof of sunspot equilibrium: need  $\Delta$ >0. Then  $K_{t+1}^L < K_{t+1}^H$ • Analysis with stochastic TFP

## Numerical simulations

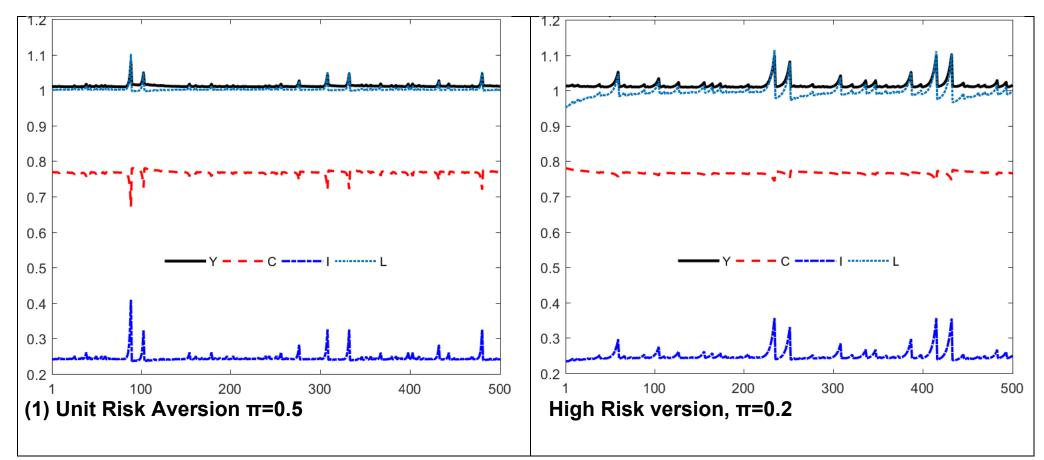
 $\beta$ =0.99;  $\alpha$ =1/3;  $\delta$ =0.025; Labor supply elasticity (at steady state) = 1.

- Log utility (unit risk aversion, RA):  $\ln(C_t)$
- 'High Risk Aversion' utility:  $\ln(C_t \overline{C}), \ \overline{C} > 0$

# Parameters of bubble process: $\Delta$ =0.001 Bust probability: $\pi$ =0.5, $\pi$ =0.2.

#### **RBC model (incomplete capital deprec.)** <u>with bubbles: predicted business cycle stati</u>stics

Un	it Risk	aversic	on <u>Hi</u> g	gh RA	_	'						
		π=0.2										
	(1)	(2)	(3)	(4)	(5)							
Standard deviations [in %]												
Y	0.49	1.16	0.68	1.43	1.81							
С	1.08	2.63	0.29	0.61	1.35							
Ι	4.29	9.38	3.22	6.51	5.30							
L	0.74	1.73	1.04	2.18	1.79							
Co	orrela	tions v	vith G	DP								
С	-0.97	-0.95	-0.99	-0.98	0.88							
Ι	0.98	0.96	0.99	0.99	0.80							
L	0.99	0.97	0.99	0.99	0.88							
Aı	itocoi	rrelatio	ons									
Y	0.36	0.63	0.35	0.62	0.84							
С	0.33	0.60	0.35	0.62	0.80							
Ι	0.36	0.63	0.37	0.64	0.87							
L	0.34	0.61	0.35	0.62	0.88							
Μ	eans [	% dev	iation	from	steady state]							
	-	2.80										
С	0.73	1.39	0.33	0.55								
Ι	3.62	7.33	4.22	7.19								
L	0.36	0.74	-0.02	-0.02								
Mean (capital income – investment)/GDP [in %]												
	`	8.75			13.42							
Fraction of periods with												
(capital income > investment) [in %]												
	99.2	96.3	99.5	97.7	100							



Non-linear RBC model (incompl. capital depreciation) driven by bubbles

Simulated GDP, C and I series normalized by steady state GDP. Hours worked (L) normalized by steady state hours.

## CONCLUSIONS

• Stationary sunspot equilibria exist in standard *non-linear* DSGE models, even when the linearized versions of those models have unique solutions.

 In the sunspot equilibria considered here, the economy temporarily diverges from the nosunspots trajectory, before abruptly reverting towards that trajectory.

 In contrast to rational bubbles in linear models (Blanchard (1979)), the bubbles considered here are stationary--their expected path does not explode to infinity.

#### **ADDITIONAL MATERIAL** Blanchard (1979):

 $E_t y_{t+1} = \lambda \cdot y_t, \quad \lambda > 1 \implies y_{t+1} = \lambda \cdot y_t + \varepsilon_{t+1}, \quad E_t \varepsilon_{t+1} = 0$ How non-linearity may generate stationary bubble: Assume:  $E_t \exp(z_{t+1} - \lambda z_t) = a$ ,  $\lambda > 1$ , a > 0 $\Rightarrow \exp(z_{t+1} - \lambda z_t) = a + \eta_{t+1}$  with  $E_t \eta_{t+1} = 0$  $\Rightarrow z_{t+1} = \lambda z_t + \log(a + \eta_{t+1})$ . Let  $y_t \equiv z_t + \ln(a)/(\lambda - 1)$ ,  $\varepsilon_{t+1} \equiv \eta_{t+1}/a$  $\Rightarrow y_{t+1} = \lambda \cdot y_t + \ln(1 + \varepsilon_{t+1}), \quad E_t \varepsilon_{t+1} = 0$  $y_{t+1}$  is <u>concave</u> in  $\mathcal{E}_{t+1} \Rightarrow E_t y_{t+1} < \lambda \cdot y_t$ Let  $\mathcal{E}_{t+1} \in \{-\mathcal{E}_t; \mathcal{E}_t \pi/(1-\pi)\}$  with prob.  $\pi, 1-\pi$ .  $\mathcal{E}_t > 0$ Set  $\mathcal{E}_t \in [0,1)$  so that  $y_{t+1} = \lambda \cdot y_t + \ln(1 - \mathcal{E}_t) = \Delta < 0$  $y_{t+1} = y_{t+1}^{H} \equiv \lambda \cdot y_{t} + \ln\{1 + [1 - \exp(\Delta - \lambda \cdot y_{t})] \cdot \pi / (1 - \pi)\}$  with prob.  $1 - \pi$  $y_{t+1} = \Delta$  with probability  $\pi$